Holographic Renormalized Entanglement Entropy William Woodhead Southampton STAG

1. Entanglement entropy

The entanglement entropy (EE) is a quantity that can be defined in any QFT whose Hilbert space \mathcal{H} can be decomposed into two or more parts:

$$\mathcal{H} = \mathcal{H}_A \times \mathcal{H}_{\overline{A}}$$

Given such a decomposition we can define the EE of subsystem Ain a state with density matrix ρ by constructing the reduced density matrix

$$ho_A = \mathsf{tr}_{\mathcal{H}_{\overline{A}}}
ho$$

The EE is then defined as the von Neumann entropy of ρ_A

$$S_A = -\mathsf{tr}\rho_A \log \rho_A$$

2. Holographic entanglement entropy

The Ryu-Takayanagi proposal claims we can calculate the EE of Aholographically by finding the area of the minimal co-dimension 2 bulk surface Σ with boundary $\partial \Sigma = \partial A$ that is homologous to A:



The entanglement entropy is then given by

$$S_A = \frac{1}{4G_N} \int_{\Sigma} d^{d-1} \sigma \sqrt{\gamma}$$

3. UV divergences

The EE is UV divergent and needs a UV cutoff to be well defined:

$$S_A = \frac{c_{2-d}}{\varepsilon^{d-2}} \operatorname{Area}(\partial A) + \dots + \begin{cases} a \log\left(\frac{R}{\varepsilon}\right) + c_0 + o(\varepsilon^0) & d \text{ even} \\ c_0 + o(\varepsilon^0) & d \text{ odd} \end{cases}$$

where c_n and a are constants, R is some characteristic length scale, arepsilon is the UV cutoff, and . . . denote subleading divergences. Notice the universal area law divergence at leading order. The coefficients a and c_0 are related to the a and F theorems in even and odd drespectively, they are scheme dependent however.

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$$S_A =$$

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5. Ho

surface

The renormalized entanglement entropy is then defined by

6. Counter terms in AdS_{D+2}

The first two terms in the counter term action for AdS_{D+2} are

Notice the first term is exactly what we expect from the area law divergence. More counter terms are needed in higher D, and logarithmic counter terms are needed in odd D.

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revious renormalization attempts

most popular renormalized EE is that of Liu & Mezei

$$\begin{cases} \frac{1}{(d-2)!!} \left(R \frac{d}{dR} - 1 \right) \left(R \frac{d}{dR} - 3 \right) \dots \left(R \frac{d}{dR} - (d-2) \right) S_A & d \text{ odd} \\ \frac{1}{(d-2)!!} R \frac{d}{dR} \left(R \frac{d}{dR} - 2 \right) \dots \left(R \frac{d}{dR} - (d-2) \right) S_A & d \text{ even} \end{cases}$$

definition is not perfect and has problems such as:

requires the geometry to have only one defining length scale,

nd does not generalise to more complex regions.

he scheme dependence is obscure.

 S_A is not finite for non-CFTs, even for relevantly deformed CFTs.

lographic renormalization

We can regularise the RT function by introducing a bulk cutoff



$$S_A = \lim_{\varepsilon \to 0} S_{A,\varepsilon} + S_{ct,\varepsilon}$$

where $S_{ct,\varepsilon}$ are covariant counter terms on $\partial \Sigma_{\varepsilon}$.

$$S_{ct,\varepsilon} = -\frac{1}{4G_N} \frac{1}{D-1} \int_{\partial \Sigma_{\varepsilon}} \sqrt{\tilde{\gamma}} \left(1 + \frac{1}{2(D-1)(D-3)} \mathcal{K}^2 \right)$$

7. Finite counter terms

We can find finite counter terms for all D, such as

More terms are possible in higher dimensions, for example

$$\int_{\partial \Sigma_{\varepsilon}} d^{D-1} \sigma \sqrt{\tilde{\gamma}}$$

dependence in our results.

8. Relevant deformations

counter term action:

 $S_{ct,\varepsilon}$ =

Previous renormalization attemtps failed to capture this dependence on matter fields.

9. Relevant deformations of AdS_4

divergence appears at $\Delta = \frac{5}{2}$

to
$$O(\phi^2)$$
, and for

 $S_{c}^{(\prime)}$

 $\Delta < \frac{5}{2}$.

10. References

S. Ryu and T. Takayanagi: [arXiv:hep-th/0603001] H. Liu and M. Mezei: [arXiv:1202.2070 [hep-th]] M. Taylor and WW: to appear

$$\int_{\partial \Sigma} d^{D-1} \sigma \sqrt{\tilde{\gamma}} \mathcal{K}^{D-1}$$

$$\mathcal{R}^{(D-1)/2} \qquad \int_{\partial \Sigma_{\varepsilon}} d^{D-1} \sigma \sqrt{\tilde{\gamma}} \left(\mathcal{K}_{AB} \mathcal{K}^{AB}\right)^{(D-1)/2}$$

are both finite for odd D > 1. Such terms account for scheme

We can model RG flows by relevant deformations by adding some scalar fields $\phi_A(\rho)$ dual to a relevant scalar deformation. This introduces new divergences in the EE and so we must generalise the

$$= \int_{\partial \Sigma_{\varepsilon}} d^{D-1} \sigma \sqrt{\tilde{\gamma}} \mathcal{L}(\mathcal{R}, \mathcal{K}, \phi, \nabla \phi, \ldots)$$

For a single scalar deformation of dimension Δ , a logarithmic

$$S_{ct,\varepsilon}^{(\log)} = -\frac{1}{64G_N} \int_{\partial \Sigma_{\varepsilon}} \sqrt{\tilde{\gamma}} \phi^2 \log \varepsilon$$

 $\Delta > \frac{5}{2}$ we need the counter term

$${}^{\phi)}_{t,\varepsilon} = -\frac{1}{4G_N} \int_{\partial \Sigma_{\varepsilon}} \sqrt{\tilde{\gamma}} \frac{3-\Delta}{8(5-2\Delta)} \phi^2$$

again to $O(\phi^2)$. No ϕ dependent counter terms are needed for